Goodrive300L Series

Elevator AC Drive



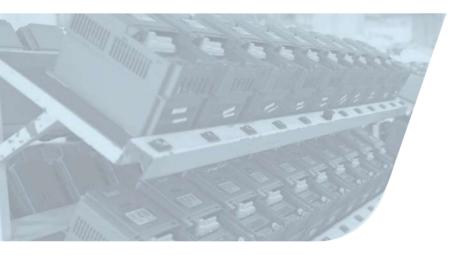








Introduction	2
Features	3
Safety	3
Comfort	3
Ease of use	3
Type designation key	5
Specifications	6
Standard wiring diagram	8
Options	9
PG card	9
I/O expansion card	11
STO card	11
Battery rescue device for emergency running	12
AC reactor	12
Filter	12
Braking unit and resistor	13
Installation dimensions	12







Introduction

Goodrive300L series elevator AC drives are the new generation AC drives developed based on INVT the latest and most advanced Goodrive300 control platform. As using TI 28-series DSP and advanced vector control technology, Goodrive300L series elevator AC drives improved great achievements in security, reliability, control performance and use functions.







Features

Safety

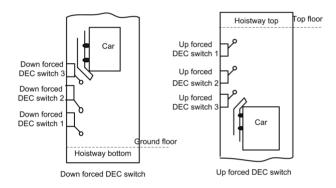
• Safe Torque Off (STO)

Support optional Built-in Safety Torque Off function, and conform to the standard and grade as follows:

		Standard	and grade		
IEC 6	1508	EN/ISO	13849-1	EN9	54-1
SIL	3	PL	е	Category	3

Forced deceleration

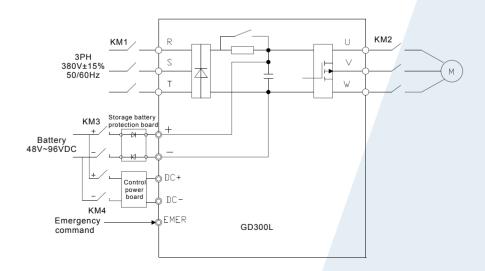
Prevent the lift from soaring to the top or diving to the bottom during the upward or downward running.



• Emergency running

When the AC power failur, the contol system connects the UPS (voltage ≥ 300V) or battery (48V ≤ voltage ≤ 96V) to the main circuit terminals (+) and (-) of the AC drive by the bypass switch. The AC drive implements automatic adjacent levelling and shutdown after eceiving the emergency running speed and running direction commands (FWD/REV).

Note: When using the emergency running function, battery rescue devicenced to be selected(Refer to page 12 for details).



Wiring diagram of using battery (48V~96VDC) as emergency power

• Brake and contactor control

Control the contactor and brake based on lift running logic, enhancing lift safety performance.

Comfort

Starting torque compensation with weight sensors

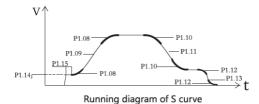
Prevent reverse slip at startup by parameter setting, ensuring stable lift startup.

• Starting torque compensation without weight sensors

Implement precise control on the gearless synchronous-tractor lifts, achieving stable startup and improving comfort.

ACC/DEC S curve algorithm

Improve comfort during motor ACC, DEC, and stop. A great parameter value corresponds to a steep S curve, while a small parameter value corresponds to a smooth S curve.



Optimized ASR

Use variable proportional and integral gain control, providing quick dynamic response in startup and stop states and improving comfort during constant-speed running.

Ease of use

Ability to drive asynchronous and synchronous motors

Can drive asynchronous or synchronous motors when the elevator working lower than 4m/s

- Support open loop control mode without encoder and closed loop control mode with encoder
- Static identification on the initial pole angle of a synchronous motor

 $Execute \ autotune \ for \ the \ permanent \ magnetic \ synchronous \ motor \ in \ static \ mode \ without \ load, \ simplifying \ commissioning.$

• Support multiple types of encoder

Support incremental, SIN/COS, absolute, and UVW encoders.

• Energy-saving running mode

Support the use of RBU, implementing energy-saving running.

Monitor and contol by upper computer software

Allow the upper computer software--INVT Studio to monitor and control the status and debug parameters in real time through Modbus communication.

Optional LCD keypad

Include two types of LCD keypads: English-Chinese bilingual LCD keypad and English-Turkish bilingual LCD keypad

Type designation key

<u>GD300L</u> - <u>5R5G</u> - <u>4</u> - <u>LIFT</u>

(1

(2)

(3)

(4)

Type designation rules

Key	Sign	Description	Remarks
Abbreviation	1	Product series abbreviation	GD300L is short for Goodrive300-LIFT
Rated power	2	Power range + Load type	5R5—5.5kW G—Constant torque load
Voltage degree	3	Voltage degree	S2: AC 1PH 220V(-15%)~240V(+10%) 4: AC 3PH 380V(-15%)~440V(+10%)
No. for market management	4	Number for market management	LIFT: AC drive special for lifts(ignorable)

Rated specifications

Model	Rated output power (kW)	Rated input current (A)	Rated output current (A)	DC reactor	Braking unit
GD300L-2R2G-S2	2.2	23	10		
GD300L-004G-4	4	13.5	9.5		
GD300L-5R5G-4	5.5	19.5	14	Optional	Standard
GD300L-7R5G-4	7.5	25	18.5	(external)	(embedded)
GD300L-011G-4	11	32	25	(externat)	(embedded)
GD300L-015G-4	15	40	32		
GD300L-018G-4	18.5	47	38	Standard	Optional
GD300L-022G-4	22	56	45	(embedded)	(external)
GD300L-030G-4	30	70	60	(embedded)	(externat)

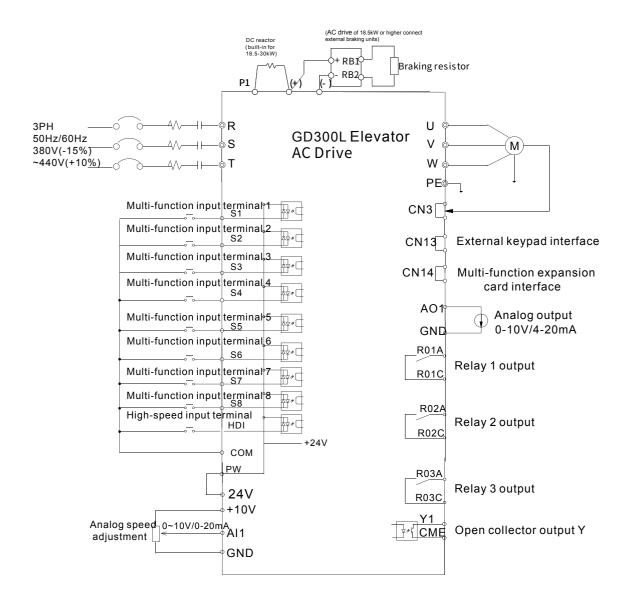
Note: If you equie other models, please contact INVT

/ Specifications

	Function	Specifications
	runction	Specifications
	Input voltage (V)	AC 1PH 220V(-15%)~240V(+10%) AC 3PH 380V(-15%) ~440V(+10%)
Power input	Input current (A)	Refer to the rated value.
	Input frequency (Hz)	50Hz or 60Hz Allowed range: 47~63Hz
	Output voltage (V)	0~input voltage
Power output	Output current (A)	Refer to the rated value.
1 ower output	Output power (kW)	Refer to the rated value.
	Output frequency (Hz)	0~400Hz
	Control mode	V/F, sensorless vector control, and sensor-included vector control
	Motor type	Asynchronous motor and permanent magnet synchronous motor
	Adjustable-speed ratio	For open-loop vector control: 1:200 For closed-loop vector control: 1:1500
	Speed control accuracy	\pm 0.5%(open-loop vector); \pm 0.05% (closed-loop vector)
Technical	Speed fluctuation	\pm 0.3% (sensorless vector control)
control	Torque response	<20ms (sensorless vector control)
	Torque control accuracy	10% (sensorless vector control)
	Starting torque	0.3Hz/150% (asynchronous-motor sensorless vector control) 0 Hz/200% (sensor-included vector control)
	Overload capability	150% of rated current: 1 minute 180% of rated current: 10 seconds 200% of rated current: 1 second
	Frequency setting method	Digital setting, analog setting, multi-step speed running setting, and MODBUS communication setting, which implement switching between setting channels
Running control	Voltage auto-adjustment	Constant voltage automatically kept when the grid voltage transients
35116.101	Fault protection	More than 30 fault protection functions against faults such as over current, overvoltage, undervoltage, overheating, phase loss and overload

	Function	Specifications
	Analog input	1 input (AI1): 0~10V/0~20mA
	Analog output	1 output (AO1): 0~10V /0~20mA
	Digital input	8 common inputs; Max. frequency: 1kHz; internal impedance: 3.3kΩ; 1 high speed input; Max. frequency: 50kHz Resolution: ≤2ms
	Digital output	1 terminal Y for open collector output
Peripheral	Relay output	3 NO programmable relay outputs RO1A NO, RO1C common terminal RO2A NO, RO2C common terminal RO3A NO, RO3C common terminal Contactor capability: 3A/AC250V, 1A/DC30V
interface	Power output	24V/200mA and 10V/50mA power output
	PG expansion card (optional)	Incremental 5~24V; SIN/COS; absolute value; UVW
	I/O expansion cards (optional)	3 for common digital input 1 for analog input AI2 1 for NO/NC relay output 1 for HDO output 1 for Y output 1 for RS-485 interface (supporting RTU)
	STO expansion car d (optional)	Provides STO security terminal functions.
	Bluetooth/Ethernet expansion card (optional)	Commissions devices through Bluetooth or Ethernet communication.
	Mountable method	Wall
	Running environment temperature	-10~50°C. The inverter must be derated if temperature is above 40°C.
	MTBF	10 years
044	Protective degree	IP20
Others	Cooling	Forced air cooling
	Braking unit	Built-in:≤15kW; optional for others
	DC reactor	Standard configuration: ≥18.5kW
	EMC filter	Optional filters C2 can be configured, meeting IEC618000-3 C2 requirements.

Standard wiring diagram



/ Options

PG card

Incremental Encoder PG card: EC-PG101-05/EC-PG101-12/EC-PG101-24

The Incremental Encoder PG card can be divided into three kinds according to the voltage of power: 5V, 12V and 24V, corresponding to the input voltage range respectively is: $4.75 \sim 10$ \, $11.75 \sim 16$ \, 24 \,

	Signal name	Description
	PWR, COM1 IA+, IA-, IB+, IB-, IZ+, IZ-	Power supply terminals Encoder signal input terminals. Support the input of the A, B, and Z signals from differential, open collectorand pull-push encoders. Voltage range: 12~15V Input frequency: 0~100kHz
1000 - 2770	OA+, OA- OB+, OB-	5V differential frequency-division output terminals. Output frequency: 0~80kHz Output impedance: 70 ohm Frequency division range: 1~256
	OA, OB	Output terminals of frequency-division push-pull signals and open-collector signals. (J1 and J2 are used to select the output signal mode.) Output frequency: 0~80kHz Output impedance: 70 ohm Frequency division range: 1~256

SIN/COS Encoder PG car d: EC-PG102-05 (DB15 Pin connector type\Terminal type)

	Signal name	Terminal identifier	Description
	A+	8	
	A-	3	
	B+	9	Encoder signal input terminals.
шиш	B-	4	Voltage range: 0.8~1.2V
The same of the sa	C+	6	Input range: 0~200kHz
	C-	1	inputrange. 0~200km2
	D+	7	
FO 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	D-	2	
	R+	15	Voltage range: 0.2~0.85V
	R-	14	Input range: 0~200kHz
	5V	12	Encoder power: 5V±5%
	0V	13	Max. output current: 300mA

UVW Encoder PG card: EC-PG103-05 (DB15 Pin connector type\Terminal type)

	Signal name	Terminal identifier	Description
	A+	8	
	A-	3	
	B+	9	Encoder differential signal input terminals.
	B-	4	Input range: 0~100kHz
THE PARTY OF THE P	Z+	15	inputrailge. 0 -100kiiz
	Z-	14	
	U+	6	
A A BOARD	U-	1	
0 0	V+	7	Encoder angle signal input terminals.
	V-	2	Input range: 0~100kHz
	W+	10	
	W-	5	
	5V	12	Encoder power: 5V±5%
	0V	13	Max. output current: 300mA

Absolute Encoder PG card: EC-PG106-05 (DB15 Pin connector type\Terminal type)

	Signal name	Terminal identifier	Description
	A+	1	
	A-	2	Encoder sine signal input terminals.
ANNOUNCE	B+	3	Input range: 0~50kHz
NAME OF THE PARTY	B-	4	
	DATA+	5	Encoder position signal input terminals.
	DATA-	6	Input range: 0~50kHz
	CLK+	11	Clock signal input terminals.
	CLK-	12	Clock signal input terminals.
	PWR	13	Encoder power: $5V \pm 5\%$
	GND	14	Max. output current: 300mA

 $Note: DB15\ pin\ connector\ type\ and\ terminal\ type\ are\ optional\ for\ all\ PG\ card\ except\ incremental\ encoder\ PG\ card.$

I/O expansion card

	Signal name	Description
	S9~S11	Digital input terminals, working with PW and COM to generate optical coupling isolation input Input voltage range: $9{\sim}30V$ Input impedance: $3.3k\Omega$
	HDO	High-speed output terminal
	+24V	24V power supply
E ELLINGULAR	PW	External power input terminal
	COM	Common terminal of +24V or external power supply
	GND	Reference zero potential of +10V
666666	Y2, CME2	Open collector output terminal, corresponding to common terminal CME2 External voltage range: 0~24V Output current range: 0~50mA
	AI2	Analog input terminal Output range: 0~10V/0~20mA (switched by J3)
	RO4A, RO4B, RO4C	Relay output: RO4A common; RO4B NC; RO4C NO Contact capacity: AC250V/3A, DC30V/1A
	RS485+ /RS485-	RS485 serial port communication terminals, supporting Modbus RTU

STO card

	Signal name	Terminal identifier	Description
	H1, 24V	STO input 1	STO redundant input terminals, externally connecting to the NC contactor If the, the response time from STO switch act to disconnect output of the inverter is
National Parties of the Control of t	H2, 24V	STO input 2	less than 50 milliseconds. The length of cable must be within 30 meters for secure. If STO is disabled, H1 and H2 can be used as S5 and S6—the digital input terminals for extended.

Battery rescue device for emergency running

When using battery (48V \sim 96VDC) as emergency power, battery rescue device is needed. It is space-saving and convenient to fix due to the integration of battery protection board and boost power board.

Total Cont	Parts	Function		
	Battery potection board	Installed diodes(D1 and D2) to protect the storage battery		
	Boots power board	Boost the voltage from the battery to power the emergency operation.		

AC reactor

Inverter model	Input AC reactor	Output AC reactor		
GD300L-004G-4	GDL-ACL0014-4CU	GDL-OCL0010-4CU		
GD300L-5R5G-4	GDL-ACL0020-4CU	GDL-OCL0014-4CU		
GD300L-7R5G-4	GDL-ACL0025-4CU	GDL-OCL0020-4CU		
GD300L-011G-4	GDL-ACL0035-4AL	GDL-OCL0025-4CU		
GD300L-015G-4	GDL-ACL0040-4AL	GDL-OCL0035-4AL		
GD300L-018G-4	GDL-ACL0051-4AL	GDL-OCL0040-4AL		
GD300L-022G-4	GDL-ACL0051-4AL	GDL-OCL0050-4AL		
GD300L-030G-4	GDL-ACL0070-4AL	GDL-OCL0060-4AL		

Filter

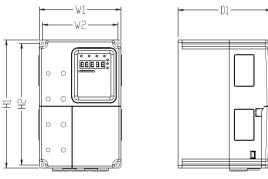
GD300L support the following optional filters, which meet EMI C2 requirement.

Inverter model	Input AC reactor	Output AC reactor		
GD300L-2R2G-S2	FLT-P04016L-B	FLT-L04016L-B		
GD300L-004G-4				
GD300L-5R5G-4				
GD300L-7R5G-4	FLT-P04032L-B	FLT-L04032L-B		
GD300L-011G-4	1 LI-F 04032L-D			
GD300L-015G-4	FLT-P04045L-B	ELT LOADAEL D		
GD300L-018G-4		FLT-L04045L-B		
GD300L-022G-4	FIT DO ADOCT D	FITTIOAOCEL D		
GD300L-030G-4	FLT-P04065L-B	FLT-L04065L-B		

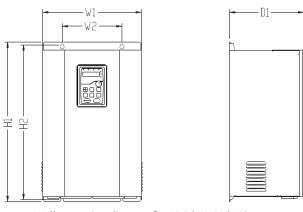
Braking unit and resistor

AC Drive model	Braking unit model	Min. braking resistor(Ω)	Recommended braking resistor(Ω)	Recommended resistor power(W)	
GD300L-004G-4		80	120	1200	
GD300L-5R5G-4	Embedded	60	80	1500	
GD300L-7R5G-4		50	60	2000	
GD300L-011G-4		35	40	3000	
GD300L-015G-4		30	32	4500	
GD300L-018G-4	DBU-055-4	25	28	5000	
GD300L-022G-4		20	22	6000	
GD300L-030G-4		16	20	10000	

/ Installation dimensions



Wall mounting diagram for 1.5 kW~15 kW inverters

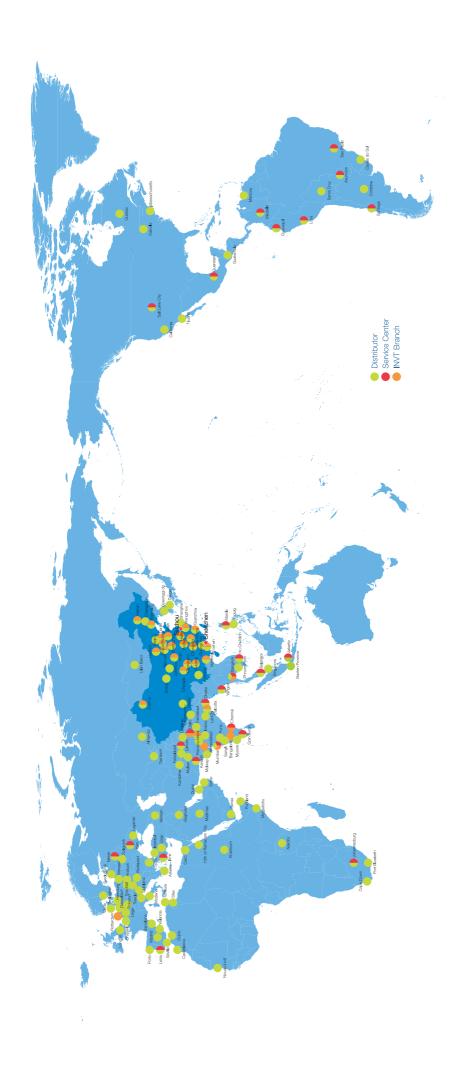


Wall mounting diagram for 18.5 kW~30 kW inverters

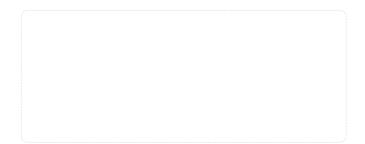
Wall-mounting dimensions for 380V inverters (unit: mm)

O	•	•				
Model	W1	W2	H1	H2	D1	Installation hole (d)
1.5kW~5.5kW	160	147.5	250	237.5	175	5
7.5kW~15kW	220	206	320	305.5	180	6
18.5kW~30kW	290	176	470	455.5	220	6.5

invt



Your Trusted Industry Automation Solution Provider











DCIM



E-mail:overseas@invt.com.cn

INVT Guangming Technology Building, Songbai Road, Matian, Guangming District, Shenzhen, China

Website:www.invt.com

SHENZHEN INVT ELECTRIC CO.,LTD.

• Elevator Intelligent Control System

Industrial Automation:

Servo System

• Rail Transit Traction System

• UPS

• Solar Inverter

• New Energy Vehicle Powertrain System

• New Energy Vehicle Charging System

• New Energy Vehicle Motor

INVT Copyright.

Electric Power: